Carpathian Math. Publ. 2020, 12 (1), 23-33 doi:10.15330/cmp.12.1.23-33



http://www.journals.pnu.edu.ua/index.php/cmp Карпатські матем. публ. 2020, Т.12, №1, С.23-33

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NONLOCAL INVERSE BOUNDARY-VALUE PROBLEM FOR A 2D PARABOLIC **EQUATION WITH INTEGRAL OVERDETERMINATION CONDITION**

This article studies a nonlocal inverse boundary-value problem for a two-dimensional secondorder parabolic equation in a rectangular domain. The purpose of the article is to determine the unknown coefficient and the solution of the considered problem. To investigate the solvability of the inverse problem, we transform the original problem into some auxiliary problem with trivial boundary conditions. Using the contraction mappings principle, existence and uniqueness of the solution of an equivalent problem are proved. Further, using the equivalency, the existence and uniqueness theorem of the classical solution of the original problem is obtained.

Key words and phrases: inverse problem, two-dimensional parabolic equation, Fourier method, classical solution, overdetermination condition.

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INTRODUCTION AND FORMULATION OF THE INVERSE PROBLEM

In the present paper, we consider an inverse boundary-value problem for a two-dimensional parabolic equation in a rectangular domain. The main goal of this article is to prove the existence and uniqueness of a classical solution of an inverse boundary-value problem.

The inverse problems arise in many different areas of mathematical modeling types, such as mineral exploration, biology, medicine, seismology, desalination of seawater, movement of liquid in a porous medium, financial market behavior, etc. Fundamentals of the theory and practice of research of inverse problems were established and developed in the pioneering works of Tikhonov [18], Lavrent'ev [15], Ivanov [10], Romanov [17], Denisov [3,4]. Recently, there have been many studies of inverse problems for 1D parabolic and other types of equations. A more detailed bibliography and a classification of problems may be found in [1,2,6,7,11,12].

Problems of the solvability of inverse problems for a two-dimensional heat equation is extensively studied by many authors, see, for example, Ismailov [5], Ivanchov [8,9], Kabanikhin [13], Kinash [14], Zaynullov [19], and others. But the statement of the problem and the proof techniques used in this study are different from representations in these papers.

Motivated by these works, we study in this paper the existence and uniqueness of a classical solution for the following inverse problem: in the domain $D_T = \bar{Q}_{xy} \times [0, T]$, where $Q_{xy} =$ $\{(x,y): 0 < x < 1, 0 < y < 1\}$, consider a two-dimensional parabolic equation

$$u_t(x,y,t) - c(t)(u_{xx}(x,y,t) + u_{yy}(x,y,t)) = a(t)u(x,y,t) + f(x,y,t), (x,y,t) \in D_T,$$
 (1)

УДК 517.95

2010 Mathematics Subject Classification: 35R30, 35K20, 35A09, 35A02.

with the nonlocal condition

$$u(x,y,0) + \delta u(x,y,T) = \varphi(x,y), \qquad (x,y) \in \bar{Q}_{xy}, \tag{2}$$

the boundary conditions

$$u(0, y, t) = u_x(1, y, t) = 0, \qquad 0 \le y \le 1, \ 0 \le t \le T,$$
 (3)

$$u_y(x,0,t) = u(x,1,t) = 0, \qquad 0 \le x \le 1, \ 0 \le t \le T,$$
 (4)

and the overdetermination condition

$$u(x_0, y_0, t) + \int_0^1 \int_0^1 K(x, y)u(x, y, t)dxdy = h(t), \qquad 0 \le t \le T, \ 0 < x_0, y_0 < 1, \tag{5}$$

where $\delta \ge 0$ is known number, $(x_0, y_0) \in Q_{xy}$ is some fixed point, 0 < c(t), f(x, y, t), $\varphi(x, y)$, h(t) are given functions, u(x, y, t) and a(t) are unknown functions.

Definition 1. The pair $\{u(x,y,t),a(t)\}$ is said to be a classical solution of the problem (1)–(5), if the functions $u(x,y,t) \in C^{2,2,1}(D_T)$ and $a(t) \in C[0,T]$ satisfy equation (1) in D_T , and the conditions (2)–(5) in the classical (usual) sense.

To investigate the existence and uniqueness of the classical solution of problem (1)–(5), we prove the following theorem.

Theorem 1. Suppose that $\delta \geq 0$, $f(x,y,t) \in C(D_T)$, $\varphi(x,y) \in C(\bar{Q}_{xy})$, $K(x,y) \in L_1(Q_{xy})$, $h(t) \in C^1[0,T]$, $h(t) \neq 0$, $0 \leq t \leq T$ and the compatibility condition

$$\varphi(x_0, y_0) + \int_0^1 \int_0^1 K(x, y) \varphi(x, y) \, dx \, dy = h(0) + \delta h(T), \tag{6}$$

holds true. Then the problem of finding a classical solution of (1)–(5) is equivalent to the problem of determining the functions $u(x,y,t) \in C^{2,2,1}(D_T)$ and $a(t) \in C[0,T]$, satisfying (1)–(4), and the condition

$$h'(t) - c(t) \left(u_{xx}(x_0, y_0, t) + u_{yy}(x_0, y_0, t) + \int_0^1 \int_0^1 K(x, y) (u_{xx}(x, y, t) + u_{yy}(x, y, t)) dx dy \right)$$

$$= a(t)h(t) + f(x_0, y_0, t) + \int_0^1 \int_0^1 K(x, y) f(x, y, t) dx dy, \qquad 0 \le t \le T.$$
(7)

Proof. Let $\{u(x,y,t),a(t)\}$ be the classical solution of problem (1)–(5). Then from equation (1), we have

$$\frac{d}{dt} \left(u(x_0, y_0, t) + \int_0^1 \int_0^1 K(x, y) u(x, y, t) dx dy \right) \\
- c(t) \left(u_{xx}(x_0, y_0, t) + u_{yy}(x_0, y_0, t) + \int_0^1 \int_0^1 K(x, y) (u_{xx}(x, y, t) + u_{yy}(x, y, t)) dx dy \right)$$

$$= a(t) \left(u(x_0, y_0, t) + \int_0^1 \int_0^1 K(x, y) u(x, y, t) \, dx \, dy \right)$$

$$+ f(x_0, y_0, t) + \int_0^1 \int_0^1 K(x, y) f(x, y, t) \, dx \, dy, \qquad 0 \le t \le T.$$
(8)

Differentiating both sides of (6) with respect to *t* gives

$$\frac{d}{dt}\left(u(x_0, y_0, t) + \int_0^1 \int_0^1 K(x, y)u(x, y, t) \, dx \, dy\right) = h'(t), \qquad 0 \le t \le T. \tag{9}$$

From (8), taking into account (5) and (9), we arrive at (7).

Now, assume that $\{u(x, y, t), a(t)\}$ is a solution to the problem (1)–(4), (7). Then from (7) and (8), we get

$$\frac{d}{dt} \left(u(x_0, y_0, t) + \int_0^1 \int_0^1 K(x, y) u(x, y, t) \, dx \, dy - h(t) \right)
= a(t) \left(u(x_0, y_0, t) + \int_0^1 \int_0^1 K(x, y) u(x, y, t) \, dx \, dy - h(t) \right), \quad 0 \le t \le T.$$
(10)

Using (2) and the compatibility condition (6), we obtain the following relation

$$u(x_{0}, y_{0}, 0) + \int_{0}^{1} \int_{0}^{1} K(x, y)u(x, y, 0) dx dy - h(0)$$

$$+ \delta \left(u(x_{0}, y_{0}, T) + \int_{0}^{1} \int_{0}^{1} K(x, y)u(x, y, T) dx dy - h(T) \right)$$

$$= u(x_{0}, y_{0}, 0) + \delta u(x_{0}, y_{0}, T) + \int_{0}^{1} \int_{0}^{1} K(x, y)(u(x, y, 0) + u(x, y, T)) dx dy$$

$$- (h(0) + \delta h(T)) = \varphi(x_{0}, y_{0}) + \int_{0}^{1} \int_{0}^{1} K(x, y)\varphi(x, y) dx dy - (h(0) + \delta h(T)) = 0.$$
(11)

It is clear that the general solution of equation (10) has the form

$$u(x_0, y_0, t) + \int_0^1 \int_0^1 K(x, y) u(x, y, t) dx dy - h(t) = ce^{\int_0^t a(\tau) d\tau},$$
 (12)

where *c* is an arbitrary constant.

Hence, using (11), we find

$$c\left(1+\delta e^{-\int_{0}^{T}a(\tau)d\tau}\right)=0.$$
(13)

By virtue of $\delta \geq 0$, from (13), we obtain that c = 0. Setting c = 0 in (12), we conclude that

$$u(x_0, y_0, t) + \int_0^1 \int_0^1 K(x, y) u(x, y, t) dx dy - h(t) = 0, \qquad 0 \le t \le T.$$

Hence, the condition (5) is satisfied. The proof is complete.

2 SOLVABILITY OF THE INVERSE BOUNDARY-VALUE PROBLEM

We seek the first component u(x, y, t) of classical solution $\{u(x, y, t), a(t)\}$ of the problem (1)–(4), (7) in the form

$$u(x,y,t) = \sum_{k=1}^{\infty} \sum_{n=1}^{\infty} u_{k,n}(t) \sin \lambda_k x \cos \gamma_n y,$$

$$\lambda_k = \frac{\pi}{2} (2k-1), \quad \gamma_n = \frac{\pi}{2} (2n-1), \quad k, n = 1, 2, \dots,$$
(14)

where

$$u_{k,n}(t) = 4 \int_0^1 \int_0^1 u(x,y,t) \sin \lambda_k x \cos \gamma_n y \, dx \, dy.$$

Applying the formal scheme of the Fourier method, from (1) and (2), we have

$$u'_{k,n}(t) + (\lambda_k^2 + \gamma_n^2)c(t)u_{k,n}(t) = F_{k,n}(t; u, a), \qquad 0 \le t \le T,$$
(15)

$$u_{k,n}(0) + \delta u_{k,n}(T) = \varphi_{k,n}, \qquad k, n = 1, 2, \dots,$$
 (16)

where

$$F_{k,n}(t;u,a) = f_{k,n}(t) + a(t)u_{k,n}(t),$$

$$f_{k,n}(t) = 4 \int_0^1 \int_0^1 f(x,y,t) \sin \lambda_k x \cos \gamma_n y \, dx \, dy, \qquad \varphi_{k,n} = 4 \int_0^1 \int_0^1 \varphi(x,y) \sin \lambda_k x \cos \gamma_n y \, dx \, dy.$$

Solving problem (15), (16), we find

$$u_{k,n}(t) = \frac{\varphi_{k,n}e^{-\int_{0}^{t}\mu_{k,n}^{2}c(s)ds}}{1 + \delta e^{-\int_{0}^{T}\mu_{k,n}^{2}c(s)ds}} + \int_{0}^{t}F_{k,n}(\tau;u,a)e^{-\int_{\tau}^{t}\mu_{k,n}^{2}c(s)ds}d\tau$$

$$-\frac{\delta e^{-\int_{0}^{T}\mu_{k,n}^{2}c(s)ds}}{1 + \delta e^{-\int_{0}^{T}\mu_{k,n}^{2}c(s)ds}} \int_{0}^{T}F_{k,n}(\tau;u,a)e^{-\int_{\tau}^{t}\mu_{k,n}^{2}c(s)ds}d\tau,$$

$$1 + \delta e^{-\int_{0}^{T}\mu_{k,n}^{2}c(s)ds} \int_{0}^{T}F_{k,n}(\tau;u,a)e^{-\int_{\tau}^{t}\mu_{k,n}^{2}c(s)ds}d\tau,$$

$$1 + \delta e^{-\int_{0}^{T}\mu_{k,n}^{2}c(s)ds}\int_{0}^{T}F_{k,n}(\tau;u,a)e^{-\int_{\tau}^{t}\mu_{k,n}^{2}c(s)ds}d\tau,$$

$$1 + \delta e^{-\int_{0}^{T}\mu_{k,n}^{2}c(s)ds}\int_{0}^{T}F_{k,n}(\tau;u,a)e^{-\int_{\tau}^{t}\mu_{k,n}^{2}c(s)ds}d\tau,$$

where

$$\mu_{kn}^2 = \lambda_k^2 + \gamma_n^2.$$

Substituting the expressions $u_{k,n}(t)$ (k, n = 1, 2, ...) described by (17) into (14), to determine the first component of the solution (1)–(4), (7), we obtain

$$u(x,y,t) = \sum_{k=1}^{\infty} \sum_{n=1}^{\infty} \left\{ \frac{\varphi_{k,n} e^{-\int_{0}^{t} \mu_{k,n}^{2} c(s) ds}}{1 + \delta e^{-\int_{0}^{T} \mu_{k,n}^{2} c(s) ds}} + \int_{0}^{t} F_{k,n}(\tau;u,a) e^{-\int_{\tau}^{t} \mu_{k,n}^{2} c(s) ds} d\tau - \frac{\int_{0}^{t} \mu_{k,n}^{2} c(s) ds}{1 + \delta e^{-\int_{0}^{T} \mu_{k,n}^{2} c(s) ds}} \int_{0}^{T} F_{k,n}(\tau;u,a) e^{-\int_{\tau}^{t} \mu_{k,n}^{2} c(s) ds} d\tau \right\} \sin \lambda_{k} x \cos \gamma_{n} y.$$

$$\left. 1 + \delta e^{-\int_{0}^{T} \mu_{k,n}^{2} c(s) ds} \int_{0}^{T} F_{k,n}(\tau;u,a) e^{-\int_{\tau}^{t} \mu_{k,n}^{2} c(s) ds} d\tau \right\} \sin \lambda_{k} x \cos \gamma_{n} y.$$

$$\left. 1 + \delta e^{-\int_{0}^{T} \mu_{k,n}^{2} c(s) ds} \int_{0}^{T} F_{k,n}(\tau;u,a) e^{-\int_{\tau}^{t} \mu_{k,n}^{2} c(s) ds} d\tau \right\} \sin \lambda_{k} x \cos \gamma_{n} y.$$

$$\left. 1 + \delta e^{-\int_{0}^{T} \mu_{k,n}^{2} c(s) ds} \int_{0}^{T} F_{k,n}(\tau;u,a) e^{-\int_{\tau}^{t} \mu_{k,n}^{2} c(s) ds} d\tau \right\} \sin \lambda_{k} x \cos \gamma_{n} y.$$

Further from (7), taking into account $h(t) \neq 0$, we get

$$a(t) = [h(t)]^{-1} \left\{ h'(t) - \left(f(x_0, y_0, t) + \int_0^1 \int_0^1 K(x, y) f(x, y, t) \, dx \, dy \right) - c(t) \sum_{k=1}^\infty \sum_{n=1}^\infty u_{k,n}(t) p_{k,n} \right\},$$
(19)

where

$$p_{k,n} = \mu_{k,n}^2 \left(\sin \lambda_k x_0 \cos \gamma_n y_0 + \int_0^1 \int_0^1 K(x,y) \sin \lambda_k x \cos \gamma_n y \, dx \, dy \right).$$

Next, substituting the expressions $u_{k,n}(t)$ (k, n = 1, 2, ...) represented by (17) into (19), to find the second component of the solution (1)–(4), (7), we have

$$a(t) = [h(t)]^{-1} \left\{ h'(t) - \left(f(x_0, y_0, t) + \int_0^1 \int_0^1 K(x, y) f(x, y, t) \, dx \, dy \right) - c(t) \sum_{k=1}^\infty \sum_{n=1}^\infty \left[\frac{\varphi_{k,n} e^{-\int_0^t \mu_{k,n}^2 c(s) ds}}{1 + \delta e^{-\int_0^T \mu_{k,n}^2 c(s) ds}} + \int_0^t F_{k,n}(\tau; u, a) e^{-\int_\tau^t \mu_{k,n}^2 c(s) ds} \, d\tau \right] - \frac{\delta e^{-\int_0^T \mu_{k,n}^2 c(s) ds}}{1 + \delta e^{-\int_0^T \mu_{k,n}^2 c(s) ds}} \int_0^T F_{k,n}(\tau; u, a) e^{-\int_\tau^t \mu_{k,n}^2 c(s) ds} \, d\tau \right] p_{k,n} \right\}.$$

$$\left\{ h'(t) - \left(f(x_0, y_0, t) + \int_0^1 \int_0^1 K(x, y) f(x, y, t) \, dx \, dy \right) \right\}$$

$$- \frac{\delta e^{-\int_0^T \mu_{k,n}^2 c(s) ds}}{1 + \delta e^{-\int_0^T \mu_{k,n}^2 c(s) ds}} \int_0^T F_{k,n}(\tau; u, a) e^{-\int_\tau^t \mu_{k,n}^2 c(s) ds} \, d\tau \right] p_{k,n} \right\}.$$

Thus, the solution of problem (1)–(4), (7) was reduced to the solution by systems (18), (20) with respect to unknown functions u(x, y, t) and a(t).

Proceeding from the definition of the solution of the problem (1)–(4), (7) the following statement is proved.

Lemma 1. If $\{u(x,y,t), a(t)\}$ is any solution of (1)–(4), (7) then the functions

$$u_{k,n}(t) = 4 \int_{0}^{1} \int_{0}^{1} u(x, y, t) \sin \lambda_k x \cos \gamma_n y \, dx \, dy, \qquad k, n = 1, 2, \dots,$$

satisfy the system (17) on the interval [0, T].

Proof. Let $\{u(x, y, t), a(t)\}$ be any solution of problem (1)–(4), (7). Multiplying both sides of the equation (1) by function $4 \sin \lambda_k x \cos \gamma_n y$ (k, n = 1, 2, ...) and integrating both sides with respect to x and y from 0 to 1, and using relationships

$$4\int_{0}^{1}\int_{0}^{1}u_{t}(x,y,t)\sin\lambda_{k}x\cos\gamma_{n}y\,dx\,dy = \frac{d}{dt}\left(4\int_{0}^{1}\int_{0}^{1}u(x,y,t)\sin\lambda_{k}x\cos\gamma_{n}y\,dx\,dy\right) = u'_{k,n}(t),$$

$$4\int_{0}^{1}\int_{0}^{1}\left(u_{xx}(x,y,t)+u_{yy}(x,y,t)\right)\sin\lambda_{k}x\cos\gamma_{n}y\,dx\,dy$$

$$= -(\lambda_k^2 + \gamma_n^2) \left(4 \int_0^1 \int_0^1 u(x, y, t) \sin \lambda_k x \cos \gamma_n y \, dx \, dy \right) = -(\lambda_k^2 + \gamma_n^2) u_{k,n}(t), \quad k, n = 1, 2, \dots,$$

we get that the equation (15) is satisfied.

Similarly, from (2) we obtain that condition (16) is satisfied. Thus, $u_{k,n}(t)$, k, n = 1, 2, ..., is a solution to the problem (15), (16). Hence, it straightforward follows that the functions $u_{k,n}(t)$, k, n = 1, 2, ..., satisfy on [0, T] system (17). Thus the lemma is proved.

Obviously, if

$$u_{k,n}(t) = 4 \int_{0}^{1} \int_{0}^{1} u(x, y, t) \sin \lambda_k x \cos \gamma_n y \, dx \, dy, \qquad k, n = 1, 2, \dots,$$

is a solution to system (17), then the functions

$$u(x,y,t) = \sum_{k=1}^{\infty} \sum_{n=1}^{\infty} u_{k,n}(t) \sin \lambda_k x \cos \gamma_n y,$$

and a(t) is a solution of system (18), (20).

From Lemma 1 it follows the next assertion.

Corollary 1. Suppose that system (18), (20) has a unique solution. Then the problem (1)–(4), (7), couldn't have more than one solution, in other words, if problem (1)–(4), (7) has a solution, then it is a unique.

In order to study the problem (1)–(4), (7), we consider the following spaces. Let $B_{2,T}^3$ denote the set of all functions of the form

$$u(x,y,t) = \sum_{k=1}^{\infty} \sum_{n=1}^{\infty} u_{k,n}(t) \sin \lambda_k x \cos \gamma_n y, \quad \lambda_k = \frac{\pi}{2} (2k-1), \quad \gamma_n = \frac{\pi}{2} (2n-1), \quad k, n = 1, 2, \ldots,$$

considered in domain D_T , where the functions $u_{k,n}(t)$, k, n = 1, 2, ..., are continuous on [0, T], and satisfy the condition

$$\left\{ \sum_{k=1}^{\infty} \sum_{n=1}^{\infty} \left(\mu_{k,n}^3 \| u_{k,n}(t) \|_{C[0,T]} \right)^2 \right\}^{\frac{1}{2}} < +\infty.$$

The norm in the space $B_{2,T}^3$ is defined as follows

$$||u(x,y,t)||_{B_{2,T}^3} = \left\{ \sum_{k=1}^{\infty} \sum_{n=1}^{\infty} \left(\mu_{k,n}^3 ||u_{k,n}(t)||_{C[0,T]} \right)^2 \right\}^{\frac{1}{2}}.$$

We denote by E_T^3 the topological product of $B_{2,T}^3 \times C[0,T]$. The norm of the element $z = \{u,a\}$ is determined by the formula

$$||z||_{E_T^3} = ||u(x,y,t)||_{B_{2,T}^3} + ||a(t)||_{C[0,T]}.$$

It is known [16] that the spaces $B_{2,T}^3$ and E_T^3 are Banach spaces. Now, consider the operator

$$\Phi(u,a) = \{\Phi_1(u,a), \Phi_2(u,a)\}$$

in the space E_T^3 , where

$$\Phi_1(u,a) = \tilde{u}(x,y,t) = \sum_{k=1}^{\infty} \sum_{n=1}^{\infty} \tilde{u}_{k,n}(t) \sin \lambda_k x \cos \gamma_n y,$$

$$\Phi_2(u,a) = \tilde{a}(t),$$

and the functions $\tilde{u}_{k,n}(t)$, $k, n = 1, 2, ..., \tilde{a}(t)$ are equal to the right-hand sides of (17), (20) respectively.

It is easy to see that

$$1 + \delta e^{-\int_{0}^{T} \frac{\lambda_{k}^{2}\beta(s) ds}{1 + \lambda_{k}^{2}\alpha(s)}} \ge 1,$$

$$\mu_{k,n}^{3} \le (\lambda_{k}^{2} + \gamma_{k}^{2})(\lambda_{k} + \gamma_{n}) = \lambda_{k}^{3} + \lambda_{k}^{2}\gamma_{n} + \gamma_{k}^{2}\lambda_{k} + \gamma_{n}^{3},$$

$$\int_{0}^{T} |f_{k,n}(\tau)| d\tau \le \sqrt{T} \left(\int_{0}^{T} |f_{k,n}(\tau)|^{2} d\tau \right)^{\frac{1}{2}},$$

$$|p_{k,n}| = \left(1 + \int_{0}^{1} \int_{0}^{1} |K(x,y)| dx dy \right) \mu_{k,n}^{2} \equiv p\mu_{k,n}^{2}.$$

Taking into consideration these relations, we have

$$\left\{ \sum_{n=1}^{\infty} \sum_{k=1}^{\infty} \left(\mu_{k,n}^{3} \| \tilde{u}_{k,n}(t) \|_{C[0,T]} \right)^{2} \right\}^{\frac{1}{2}} \leq 3 \left(\sum_{n=1}^{\infty} \sum_{k=1}^{\infty} \left(\lambda_{k}^{3} | \varphi_{k,n} | \right)^{2} \right)^{\frac{1}{2}} \\
+ 3 \left(\sum_{n=1}^{\infty} \sum_{k=1}^{\infty} (\lambda_{k}^{2} \gamma_{n} | \varphi_{k,n} |)^{2} \right)^{\frac{1}{2}} + 3 \left(\sum_{n=1}^{\infty} \sum_{k=1}^{\infty} (\lambda_{k} \gamma_{n}^{2} | \varphi_{k,n} |)^{2} \right)^{\frac{1}{2}} + 3 \left(\sum_{n=1}^{\infty} \sum_{k=1}^{\infty} (\gamma_{n}^{3} | \varphi_{k,n} |)^{2} \right)^{\frac{1}{2}} \\
+ 3 (1 + \delta) \left[\sqrt{T} \left(\left(\int_{0}^{T} \sum_{n=1}^{\infty} \sum_{k=1}^{\infty} (\lambda_{k}^{3} | f_{k,n}(\tau) |)^{2} d\tau \right)^{\frac{1}{2}} + \left(\int_{0}^{T} \sum_{n=1}^{\infty} \sum_{k=1}^{\infty} (\lambda_{k}^{2} \gamma_{n} | f_{k,n}(\tau) |)^{2} d\tau \right)^{\frac{1}{2}} \right. \\
+ \left(\int_{0}^{T} \sum_{n=1}^{\infty} \sum_{k=1}^{\infty} (\lambda_{k} \gamma_{n}^{2} | f_{k,n}(\tau) |)^{2} d\tau \right)^{\frac{1}{2}} + \left(\int_{0}^{T} \sum_{n=1}^{\infty} \sum_{k=1}^{\infty} (\gamma_{n}^{3} | f_{k,n}(\tau) |)^{2} d\tau \right)^{\frac{1}{2}} \right) \\
+ T \| a(t) \|_{C[0,T]} \left(\sum_{k=1}^{\infty} \sum_{k=1}^{\infty} (\mu_{k,n}^{3} \| u_{k,n}(t) \|_{C[0,T]})^{2} \right)^{\frac{1}{2}} \right],$$

$$\begin{split} &\|\tilde{a}(t)\|_{C[0,T]} \\ &\leq \left\| [h(t)]^{-1} \right\|_{C[0,T]} \left\{ \left\| h'(t) - \left(f(x_0, y_0, t) + \int_0^1 \int_0^1 K(x, y) f(x, y, t) \, dx \, dy \right) \right\|_{C[0,T]} \\ &+ p \, \|c(t)\|_{C[0,T]} \left(\sum_{k=1}^\infty \sum_{k=1}^\infty \mu_k^{-2} \right)^{\frac{1}{2}} \left[\left(\sum_{n=1}^\infty \sum_{k=1}^\infty (\lambda_k^3 |\varphi_{k,n}|)^2 \right)^{\frac{1}{2}} + \left(\sum_{n=1}^\infty \sum_{k=1}^\infty (\lambda_k^2 \gamma_n |\varphi_{k,n}|)^2 \right)^{\frac{1}{2}} \\ &+ \left(\sum_{n=1}^\infty \sum_{k=1}^\infty (\lambda_k \gamma_n^2 |\varphi_{k,n}|)^2 \right)^{\frac{1}{2}} + \left(\sum_{n=1}^\infty \sum_{k=1}^\infty (\lambda_k^3 \gamma_n |\varphi_{k,n}|)^2 \right)^{\frac{1}{2}} \\ &+ (1+\delta)\sqrt{T} \left(\left(\int_0^T \sum_{n=1}^\infty \sum_{k=1}^\infty (\lambda_k^3 |f_{k,n}(\tau)|)^2 d\tau \right)^{\frac{1}{2}} + \left(\int_0^T \sum_{n=1}^\infty \sum_{k=1}^\infty (\lambda_k^2 \gamma_n |f_{k,n}(\tau)|)^2 d\tau \right)^{\frac{1}{2}} \\ &+ \left(\int_0^T \sum_{n=1}^\infty \sum_{k=1}^\infty (\lambda_k \gamma_n^2 |f_{k,n}(\tau)|)^2 d\tau \right)^{\frac{1}{2}} + \left(\int_0^T \sum_{n=1}^\infty \sum_{k=1}^\infty (\gamma_n^3 |f_{k,n}(\tau)|)^2 d\tau \right)^{\frac{1}{2}} \\ &+ (1+\delta)T \, \|a(t)\|_{C[0,T]} \left(\sum_{k=1}^\infty \sum_{k=1}^\infty (\mu_{k,n}^3 \|u_{k,n}(t)\|_{C[0,T]})^2 \right)^{\frac{1}{2}} \right\}. \end{split}$$

Assume that the data for the problem (1)–(4), (7) satisfy the following conditions:

(A)
$$\varphi(x,y)$$
, $\varphi_{x}(x,y)$, $\varphi_{xx}(x,y)$, $\varphi_{y}(x,y)$, $\varphi_{xy}(x,y)$, $\varphi_{yy}(x,y) \in C(\bar{Q}_{xy})$, $\varphi_{xxy}(x,y)$, $\varphi_{xyy}(x,y)$, $\varphi_{xxx}(x,y)$, $\varphi_{yyy}(x,y) \in L_{2}(Q_{xy})$, $\varphi(0,y) = \varphi_{x}(1,y) = \varphi_{xx}(0,y) = 0$, $0 \le y \le 1$, $\varphi_{y}(x,0) = \varphi(x,1) = \varphi_{yy}(x,1) = 0$, $0 \le x \le 1$;

(B)
$$f(x,y,t)$$
, $f_x(x,y,t)$, $f_{xx}(x,y,t)$, $f_y(x,y,t)$, $f_{xy}(x,y,t)$, $f_{xy}(x,y,t)$, $f_{xy}(x,y,t)$, $f_{xxx}(x,y,t)$, $f_{yyy}(x,y,t) \in L_2(D_T)$, $f(0,y,t) = f_x(1,y,t) = f_{xx}(0,y,t) = 0$, $0 \le y \le 1$, $0 \le t \le T$, $f_y(x,0,t) = f(x,1,t) = f_{yy}(x,1,t) = 0$, $0 \le x \le 1$, $0 \le t \le T$;

(C)
$$\delta \geq 0$$
, $K(x,y) \in L_1(Q_{xy})$, $0 < c(t) \in C[0,T]$, $h(t) \in C^1[0,T]$, $h(t) \neq 0$, $0 \leq t \leq T$.

Then, from (21) and (22), respectively, we obtain

$$\|\tilde{u}(x,y,t)\|_{B_{2,T}^{3}} \le A_{1}(T) + B_{1}(T) \|a(t)\|_{C[0,T]} \|u(x,y,t)\|_{B_{2,T}^{3}}, \tag{23}$$

$$\|\tilde{a}(t)\|_{C[0,T]} \le A_2(T) + B_2(T) \|a(t)\|_{C[0,T]} \|u(x,y,t)\|_{B_{2,T}^3}, \tag{24}$$

where

$$\begin{split} A_{1}(T) &= 3 \left\| \varphi_{xxx}(x,y) \right\|_{L_{2}(Q_{xy})} + 3 \left\| \varphi_{xyy}(x,y) \right\|_{L_{2}(Q_{xy})} + 3 \left\| \varphi_{xxy}(x,y) \right\|_{L_{2}(Q_{xy})} \\ &+ 3 \left\| \varphi_{yyy}(x,y) \right\|_{L_{2}(Q_{xy})} + (1+\delta) \sqrt{T} \left. 3 \left(\left\| f_{xxx}(x,y,t) \right\|_{L_{2}(D_{T})} \right. \\ &+ 3 \left\| f_{xyy}(x,y,t) \right\|_{L_{2}(D_{T})} + 3 \left\| f_{xxy}(x,y,t) \right\|_{L_{2}(D_{T})} \\ &+ 3 \left\| f_{xxx}(x,y,t) \right\|_{L_{2}(D_{T})} + 3 \left\| f_{yyy}(x,y,t) \right\|_{L_{2}(D_{T})} \right), \\ B_{1}(T) &= 3(1+\delta)T, \end{split}$$

$$\begin{split} A_{2}(T) &= \left\| [h(t)]^{-1} \right\|_{C[0,T]} \left\{ \left\| (h'(t) - \left(f(x_{0}, y_{0}, t) + \int_{0}^{1} \int_{0}^{1} K(x, y) f(x, y, t) \, dx \, dy \right) \right\|_{C[0,T]} \right. \\ &+ p \left\| c(t) \right\|_{C[0,T]} \left(\sum_{k=1}^{\infty} \sum_{k=1}^{\infty} \mu_{k}^{-2} \right)^{\frac{1}{2}} \left[\left\| \varphi_{xxx}(x, y) \right\|_{L_{2}(Q_{xy})} + \left\| \varphi_{xyy}(x, y) \right\|_{L_{2}(Q_{xy})} \right. \\ &+ \left\| \varphi_{xxy}(x, y) \right\|_{L_{2}(Q_{xy})} + \left\| \varphi_{yyy}(x, y) \right\|_{L_{2}(Q_{xy})} + (1 + \delta) \sqrt{T} \left(\left\| f_{xxx}(x, y, t) \right\|_{L_{2}(D_{T})} \right. \\ &+ \left\| f_{xyy}(x, y, t) \right\|_{L_{2}(D_{T})} + \left\| f_{xxy}(x, y, t) \right\|_{L_{2}(D_{T})} \\ &+ \left\| f_{xxx}(x, y, t) \right\|_{L_{2}(D_{T})} + \left\| f_{yyy}(x, y, t) \right\|_{L_{2}(D_{T})} \right) \right] \right\}, \\ B_{2}(T) &= \left\| [h(t)]^{-1} \right\|_{C[0,T]} p \left\| c(t) \right\|_{C[0,T]} \left(\sum_{k=1}^{\infty} \sum_{k=1}^{\infty} \mu_{k}^{-2} \right)^{\frac{1}{2}} (1 + \delta) T. \end{split}$$

From inequalities (23) and (24) we conclude

$$\|\tilde{u}(x,y,t)\|_{B_{2,T}^{3}} + \|\tilde{a}(t)\|_{C[0,T]} \le A(T) + B(T) \|a(t)\|_{C[0,T]} \|u(x,t)\|_{B_{2,T}^{3}}, \tag{25}$$

where

$$A(T) = A_1(T) + A_2(T),$$
 $B(T) = B_1(T) + B_2(T).$

Let K_R denote the closed ball of radius R = A(T) + 2 centered at zero in E_T^3 .

Theorem 2. Let the conditions (A)–(C) and the condition

$$B(T)(A(T) + 2)^2 < 1 (26)$$

be fulfilled. Then problem (1)–(4), (7) has a unique solution in the ball K_R .

Proof. Let us consider in the space E_T^3 the equation

$$z = \Phi z, \tag{27}$$

where $z = \{u, a\}$. The components $\Phi_i(u, a)$, i = 1, 2, of operator $\Phi(u, a)$ defined by the right side of equations (18), (20), respectively. Now, consider the operator $\Phi(u, a)$ in the ball K_R of the space E_T^3 .

Similar to (25) we obtain that for any $z, z_1, z_2 \in K_R$ the following inequalities hold

$$\|\Phi z\|_{E_T^3} \le A(T) + B(T) \|p(t)\|_{C[0,T]} \|u(x,y,t)\|_{B_{2,T}^3} \le A(T) + B(T)(A(T) + 2)^2, \tag{28}$$

$$\|\Phi z_1 - \Phi z_2\|_{E_T^3} \le B(T)R(\|u_1(x,y,t) - u_2(x,y,t)\|_{B_{2,T}^3} + \|a_1(t) - a_2(t)\|_{C[0,T]}). \tag{29}$$

Then by (26), from estimates (28) and (29) it is clear that the operator Φz acts in a ball K_R and satisfy the conditions of the contraction mapping principle. Therefore the operator Φz has a unique fixed point $\{u,a\}$ in the ball K_R , which is a unique solution of equation (27), i.e., $\{u,a\}$ is a unique solution of the systems (18), (20) in the ball K_R .

The function u(x, y, t) as an element of the space E_T^3 is continuous and has continuous derivatives $u_x(x, y, t)$, $u_{xx}(x, y, t)$, $u_y(x, y, t)$, $u_{xy}(x, y, t)$, $u_{yy}(x, y, t)$ in D_T .

From the equation (15) it is clear that

$$\begin{aligned} u_{k,n}'(t) + (\lambda_k^2 + \gamma_n^2)c(t)u_{k,n}(t) &= F_{k,n}(t;u,a), \quad 0 \le t \le T, \\ \left\{ \sum_{n=1}^{\infty} \sum_{k=1}^{\infty} \left(\mu_{k,n} \left\| u_{k,n}'(t) \right\|_{C[0,T]} \right)^2 \right\}^{\frac{1}{2}} &\le \sqrt{2} \left\| c(t) \right\|_{C[0,T]} \left\| u(x,y,t) \right\|_{B_{2,T}^3} \\ &+ \left\| \left\| f_x(x,y,t) + f_y(x,y,t) + p(t)(u_x(x,y,t) + u_y(x,y,t)) \right\|_{C[0,T]} \right\|_{L_2(Q_{xy})}. \end{aligned}$$

Thus $u_t(x, y, t)$ is continuous in D_T .

It is not hard to verify that equation (1) and conditions (2)–(4), (7) are satisfied in the usual sense. Thus, the solution of the problem (1)–(4), (7) is a pair of functions $\{u(x,t), a(t)\}$. By virtue of the Lemma 1, it is unique in the ball K_R . Theorem has been proved.

Thus, by Theorem 1 and Theorem 2, we arrive at the following main result.

Theorem 3. Assume that all conditions of Theorem 2 and compatibility condition

$$\varphi(x_0, y_0) + \int_0^1 \int_0^1 K(x, y) \varphi(x, y) \, dx \, dy = h(0) + \delta h(T)$$

hold. Then problem (1)–(5) has a unique classical solution in the ball K_R for sufficiently small values of T.

Acknowledgements. The authors would like to thank the anonymous referees for their careful reading of this paper and constructive suggestions that have improved the quality of our work.

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Received 29.04.2019

Азізбайов Е.І., Мехралієв Ю.Т. Нелокальна обернена крайова задача для двовимірного параболічного рівняння з інтегральною переозначеною умовою // Карпатські матем. публ. — 2020. — Т.12, \mathbb{N}^2 1. — С. 23–33.

В роботі досліджено нелокальну обернену крайову задачу для двовимірного параболічного рівняння другого порядку у прямокутній області. Метою цієї статті є визначення невідомого коефіцієнта та розв'язку вказаної задачі. Щоб дослідити роз'язність оберненої задачі, ми перетворюємо оригінальну задачу у деяку допоміжну задачу з тривіальними крайовими умовами. Використовуючи принцип стискаючих відображень, доведено існування і єдиність розв'язку для еквівалентної задачі. Використовуючи еквівалентність, отримано теорему про існування і єдиність класичного розв'язку оригінальної задачі.

Ключові слова і фрази: обернена задача, двовимірне параболічне рівняння, метод Фур'є, класичний розв'язок, переозначена умова.